

Towards Breaking Temperature Equilibrium in Multi-Component Eulerian Schemes

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- Thomas Masser
 - Ph.D. student from Stony Brook
 - Thomas's work on a computational analysis of the effect of thermal equilibrium across material interfaces has help guide the selection and analysis of the multi-temperature cell models implemented here
- Mark Christon and Robert Lowrie
 - For many helpful discussions on multi-temperature flow models and their numerical implementation
 - Jointly helped formulate the numerical schemes implemented here

The cover is taken from computational comparisons of a strong shock implosion between RAGE and the front tracking code FronTier. FronTier maintains sharp interfaces and avoids mixed cells. It fully resolves the microstructure assumed by the following flow models. The colors represent temperature and illustrate the large hot spot temperatures that can be produced by shock heating of a dense material on a light material. This computation is part of the Ph.D. work of T. Masser.

- XRAGE/FronTier are both rectangular cell based codes with a finite volume Godunov scheme update.
- XRAGE – Pressure–Temperature equilibrium equation of state:

- Conservation of total mass, momentum, and energy

$$\frac{\partial r}{\partial t} + -\Sigma(r\mathbf{u}) = 0$$

- Advection of mass fraction

$$\frac{\partial r\mathbf{u}}{\partial t} + -\Sigma(r\mathbf{u}f\mathbf{u}) + -P = 0$$

$$\frac{\partial r\left(\frac{1}{2}u^2 + e\right)}{\partial t} + -\Sigma\left(r\mathbf{u}\left(\frac{1}{2}u^2 + e\right)\right) + -\Sigma(P\mathbf{u}) = 0$$

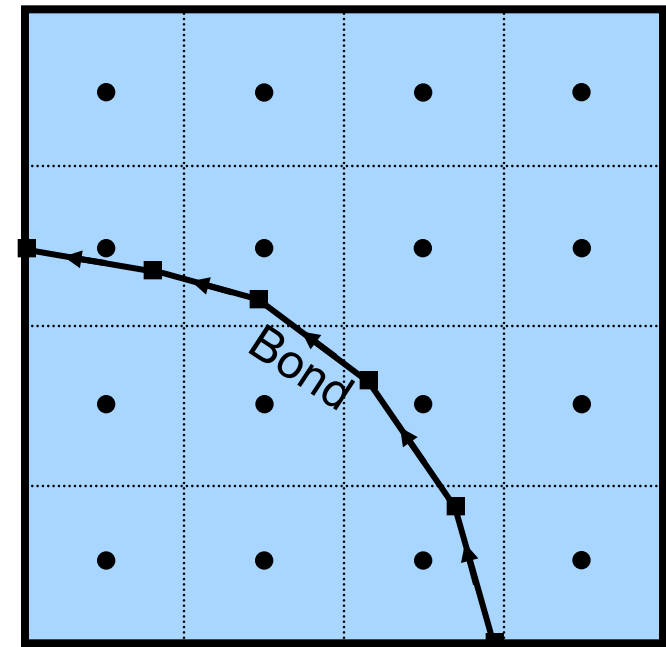
$$a_k r_k = m_k r$$

$$\frac{Dm_k}{Dt} = \frac{\partial m_k}{\partial t} + \mathbf{u} \Sigma - m_k = 0$$

Geometric Front Tracking



- Selected wave fronts are **explicitly** included in the discretization.
- The flow state consists of a composite grid with a spatial mesh overlaid with a co-dimension one mesh that **tracks** the fronts.
- The time stepping algorithm adapts to the local geometry of the front and fully couples interface motion with the spatial mesh.
- In contrast to VOF methods the interface is preserved throughout the computation
 - Interface is propagated not reconstructed
 - Separates materials for EOS treatment, no mixed cells.
- The interface is propagated using Riemann problem solutions and method of characteristic approximations.
 - Interactions are treated explicitly.



- Grid State
- Tracked Points (left,right) States

Cylindrical Implosion Test Problem Setup



Boundary Condition: $\rho = 11.233$ gram/cc, $P = 0.686$ Mbar, $\mathbf{v} = 0$

Tin: $\rho = 7.282$ gram/cc, $P = 1$ bar, $\mathbf{v} = 0$

$\Gamma = 2.27, P_{\infty} = 0.15$ Mbar, $e_{\infty} = 1.25 \times 10^{-8}$ 0.1 megajoules / gram

$\rho_0 = 7.287$ gram / cc, $C_V = 2.2 \times 10^{-6}$ 0.1 megajoules / gram / ° K, $\eta = 0.027$

Air: $\rho = 0.001047$ gram/cc, $P = 1$ bar, $\mathbf{v} = 0$

$\Gamma = 0.402, P_{\infty} = 0$ Mbar, $e_{\infty} = 0$ 0.1 megajoules/gram

$\rho_0 = 0.001047$ gram/cc, $C_V = 7.1368 \times 10^{-6}$ 0.1 megajoules/gram/°K, $\eta = 0$

Interface:

$$r = r_0 + \sum_{k=1}^9 a_k \sin \left(v_k \left(\theta + \frac{\pi}{2} \right) + \phi_k \right)$$

$\mathbf{a} = (0.208057, 0.017559, -0.0700731, -0.104933, -0.188979, 0.051327, -0.155088, -0.47643, 0.140691)$

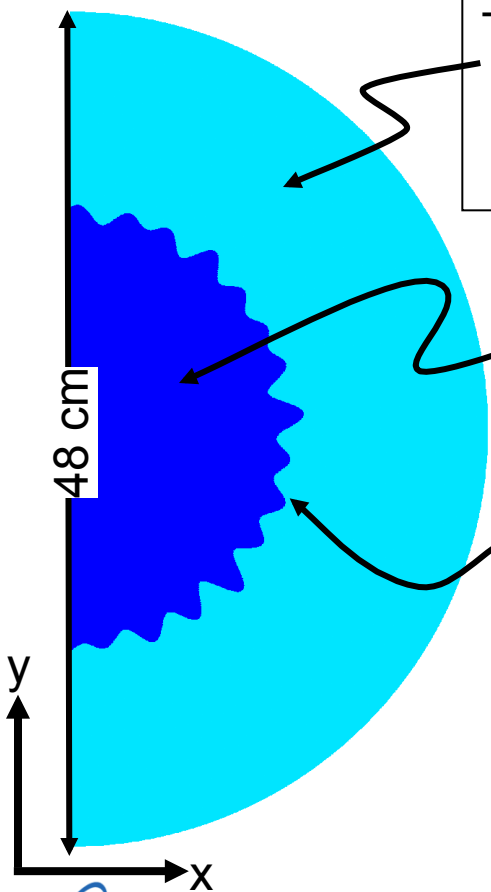
$\mathbf{v} = (16, 18, 20, 22, 24, 26, 28, 30, 32)$

$\phi = (0.945557, 4.56071, 4.85797, 6.13974, 3.09001, 4.84, 0.443656, 5.76627, 5.69294)$

EOS: Stiffened Gamma Law

$$P + (\Gamma + 1) P_{\infty} = \Gamma (e + e_{\infty}) \rho$$

$$e + e_{\infty} = C_V T + \frac{P_{\infty}}{\rho} + \eta \left(\frac{P_{\infty}}{\rho_0} \right) \left(\frac{\rho}{\rho_0} \right)^{\Gamma}$$



Temperature



Time = 0 μ sec

- Shock heating of air in an order of magnitude higher when computed by FronTier (no T equilibrium imposed).
- Prior to reshock/implosion the temperature jump across the interface is similar.
- FronTier produces a noticeably stronger reflected shock at implosion.

XSAGE-VOF

FronTier

temperature °Kelvin

7.560e+06

2.773e+06

1.017e+06

3.730e+05

1.368e+05

5.017e+04

1.840e+04

6.748e+03

2.475e+03

9.077e+02

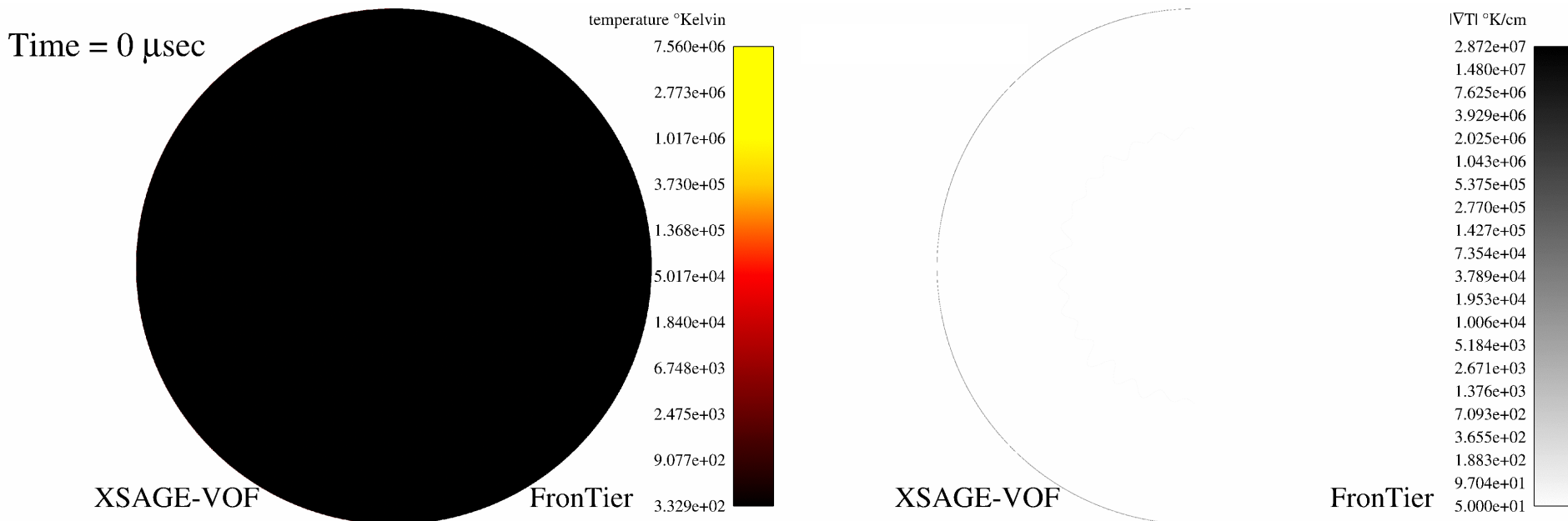
3.329e+02



Temperature



- Shock heating of air in an order of magnitude higher when computed by FronTier (no T equilibrium imposed).
- Prior to reshock/implosion the temperature jump across the interface is similar.
- FronTier produces a noticeably stronger reflected shock at implosion.



Mass Density



Time = 80 μ sec

- Tracking in both codes (VOF vs. explicit) maintain a sharp material interface until after implosion.
- After implosion XSAGE-VOF has completely mixed the materials.
- Vortex structure at late times are different.

XSAGE-VOF

FronTier

Density grams/cc

20.359283
16.317015
13.077326
10.480863
8.399921
6.732145
5.395498
4.324240
3.465676
2.777577
2.226098
1.784114
1.429883
1.145985
0.918453
0.736097
0.589947
0.472815
0.378939
0.303702
0.243403



Vorticity: $\nabla' u$



Time = 80 μsec

- Pre-implosion vorticity is similar.
- Velocity shear at interfaces supported by FronTier leads to larger vorticity values at the interface.
- Late time the vortical structure is completely different. XSAGE produces a small number of coherent vortices compared to FronTier.

XSAGE-VOF

FronTier

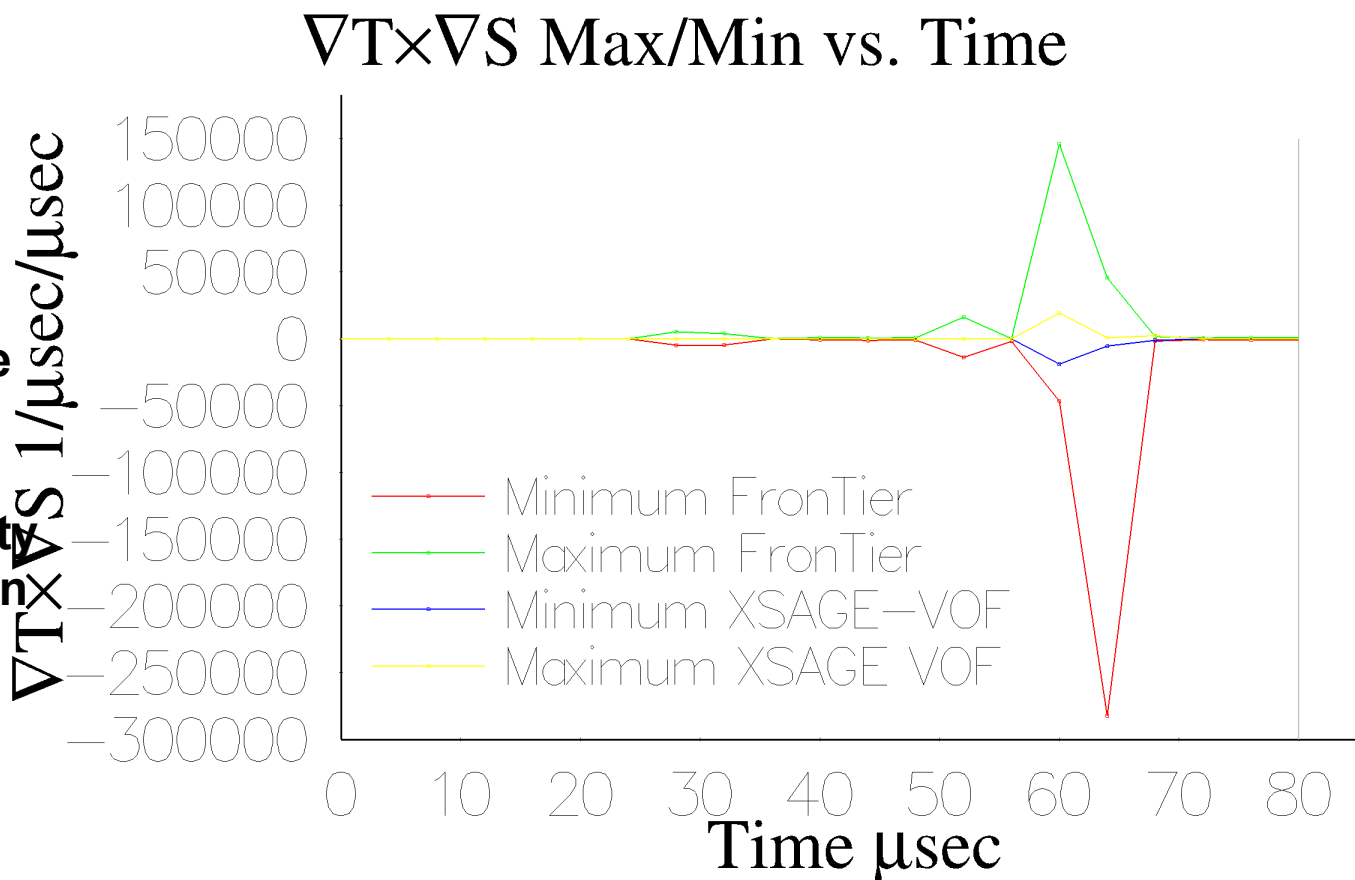
Vorticity 1/ μsec

1.00
0.90
0.80
0.70
0.60
0.50
0.40
0.30
0.20
0.10
0.00
-0.10
-0.20
-0.30
-0.40
-0.50
-0.60
-0.70
-0.80
-0.90
-1.00

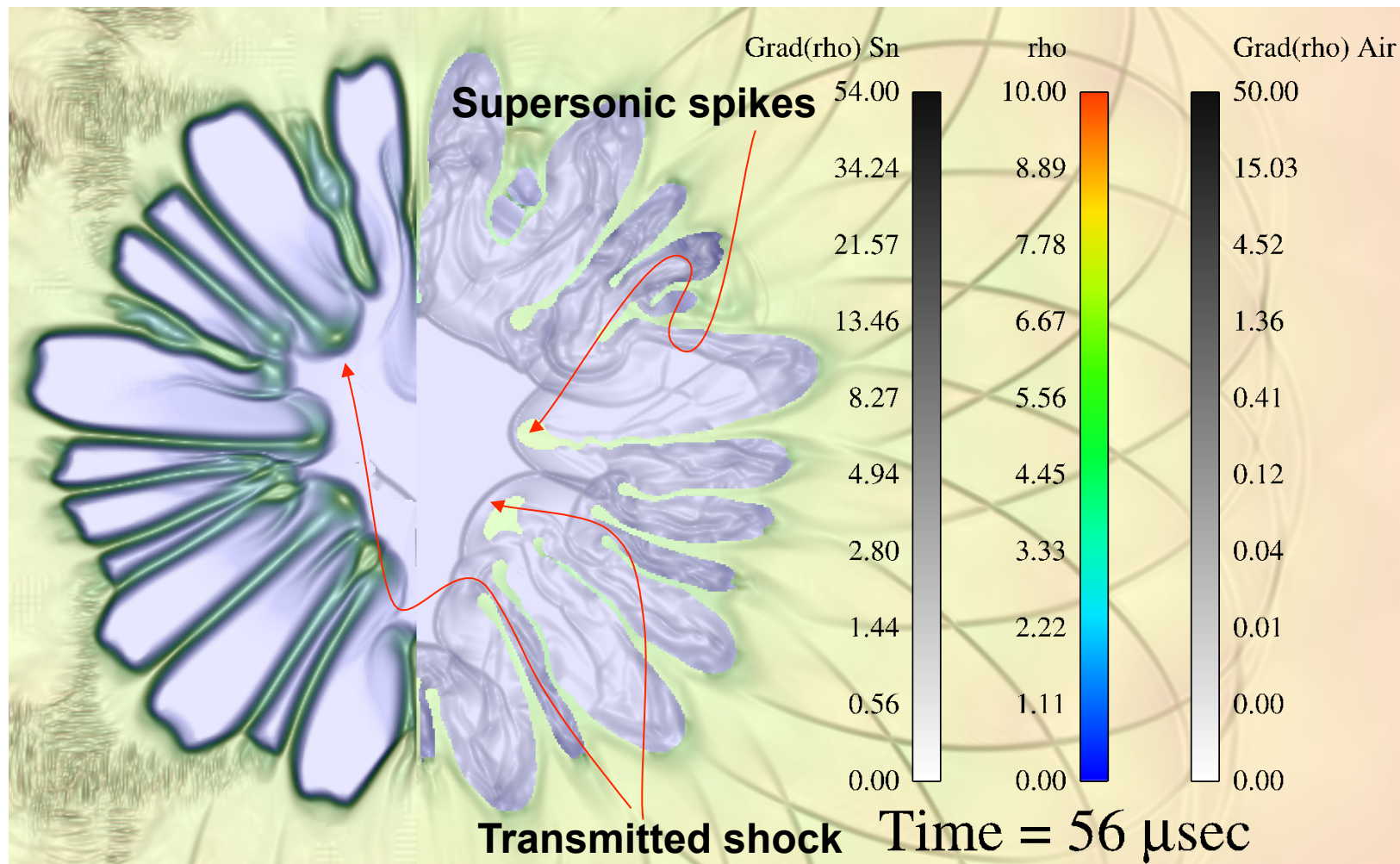
Baroclinic Vorticity Source Term, $\nabla T \times \nabla S$



- Vorticity sources are concentrated on interfaces.
- FronTier tracking together with large temperature gradients result in much large vorticity sources near air/Sn interfaces.



Blowup of Composite Image Showing Bow Shocks



Volume Fraction of Air



Time = 80 μ sec

- Volume fractions less than 10^{-10} are shown as white.
- At late time XSAGE has no cells with air volume fractions greater than a few percent. Without VOF this reduces to a fraction of a percent.

XSAGE-VOF

FronTier

Fractional Volume Air

1.00
0.95
0.90
0.85
0.80
0.75
0.70
0.65
0.60
0.55
0.50
0.45
0.40
0.35
0.30
0.25
0.20
0.15
0.10
0.05
0.00



- Clearly interface and thermal treatments can make significant differences, especially for late term mixing
- What to do?
 - Track interfaces
 - Easy in FronTier, perhaps not so easy for other codes
 - Reconstruct
 - E.g VOF
 - Still single temperature
- Enhance flow model to allow multiple temperatures

- Common methods for multi-temperature flow simulations:
 - Conserve component masses, total momentum, and total energy

$$\frac{\partial m_k r}{\partial t} + \nabla \cdot (m_k r \mathbf{u}) = 0$$

$$\frac{\partial r \mathbf{u}}{\partial t} + \nabla \cdot (r \mathbf{u} \otimes \mathbf{u}) + \nabla P = 0$$

$$\frac{\partial r \left(e + \frac{1}{2} u^2 \right)}{\partial t} + \nabla \cdot \left(r \mathbf{u} \left(e + \frac{1}{2} u^2 \right) \right) + \nabla \cdot P \mathbf{u} = 0$$

r = total mass density, m_k = mass fraction of component k , $\sum_{k=1}^N m_k = 1$

\mathbf{u} = flow velocity, P = pressure, e = total specific internal energy

- The Euler system consists of $N+D +1$ equations in $N+D+2$ unknowns.
- Closure requires specifying a relation between the dependent variables
- Pressure-Temperature Equilibrium
 - Introduce micro-quantities
 - $V_k(P, T)$: specific volume of component k
 - $e_k(P, T)$: specific internal energy of component k
 - Closure Equations: $V = \frac{1}{\rho} = \sum_{k=1}^N \hat{A}_k m_k V_k(P, T), e = \sum_{k=1}^N \hat{A}_k m_k e_k(P, T)$
 - Total system of $N+D+3$ equations in $N+D+3$ unknowns

- **P-T equilibrium:** microstructure of the mixture consists of volumetrically distinct components in local mechanical (equal velocity and pressure) and thermal equilibrium.
 - Material components are separated by interfaces/contact discontinuities across which pressure and the interfacial normal component of velocity are continuous
 - Surface tension between components in the microstructure is negligible (no capillarity due to the microstructure)
 - Shear across the microstructure interface is negligible (common velocity)
 - The simulation time scales are sufficiently long that the components have time to come into thermal equilibrium due to un-modeled processes such as thermal conduction (common temperature)

Background: Single Velocity/Single Pressure/Multiple Temperature Models



- Relax the condition of thermal equilibrium between material components by assuming each component in the microstructure has a separate temperature
- Missing $N-1$ equations to close the system
- Constitutive equations are replaced by dynamic equations (PDE's)
- Two models are considered and implemented
 - Thermal Isolation:

$$T_k \frac{DS_k}{Dt} = \frac{De_k}{Dt} + P \frac{DV_k}{Dt} = 0, \quad \frac{D}{Dt} = \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla$$

- Uniform Strain (more accurately uniform compression):

$$\frac{1}{V_k} \frac{DV_k}{Dt} = \frac{1}{V} \frac{DV}{Dt} = -\nabla \cdot \mathbf{u}, \quad 1 \leq k \leq N$$

- Models can be re-expressed as volume fraction equations:

- α_k defined by $\alpha_k V = \mu_k V_k = \mu_k V_k(P, T_k)$

- Thermal Isolation: $T_k \frac{DS_k}{Dt} = 0 \Leftrightarrow \frac{Da_k}{Dt} = a_k \left[\frac{\dot{E} r c^2}{r_k c_k^2} - \frac{1}{\delta} \sum \mathbf{u} \right], \frac{1}{r c^2} = \hat{\hat{A}} \sum_{k=1}^N \frac{a_k}{r_k c_k^2}$

- Uniform Strain: $\frac{Da_k}{Dt} = 0 \Leftrightarrow T_k \frac{DS_k}{Dt} = \frac{c_k^2}{G_k} \left[\frac{\dot{E}}{1} - \frac{r c^2}{r_k c_k^2} \sum \mathbf{u} \right], r c^2 = \frac{\hat{\hat{A}} \sum_{k=1}^N \frac{a_k}{G_k} r_k c_k^2}{\hat{\hat{A}} \sum_{k=1}^N \frac{a_k}{G_k}}$

- c_k = component sound speed, G_k = component Grüneisen exponent, and c = mixture sound speed

- Single sound speed model:

$$\frac{DP}{Dt} + r c^2 \sum \mathbf{u} = 0$$

- P-T equilibrium; compute pressure, temperature, and volume fractions given total specific volume, total specific internal energy, and mass fractions:

$$e = \sum_{k=1}^N m_k e_k(P, T), \quad V = \sum_{k=1}^N m_k V_k(P, T) \quad \text{fi} \quad \text{(PTE)}$$

$$P = P(e, V, m_1, K, m_N), T = T(e, V, m_1, K, m_N), a_k(e, V, m_1, K, m_N) = \frac{m_k V_k(P, T)}{V}$$

- Thermal Isolation and Uniform strain: compute pressure given total specific volume, total specific internal energy, mass fractions, **and** volume fractions:

$$e = \sum_{k=1}^N m_k e_k(P, V_k), \quad a_k V = m_k V_k, T_k = T_k(P, V_k) \quad \text{fi} \quad \text{(PE)}$$

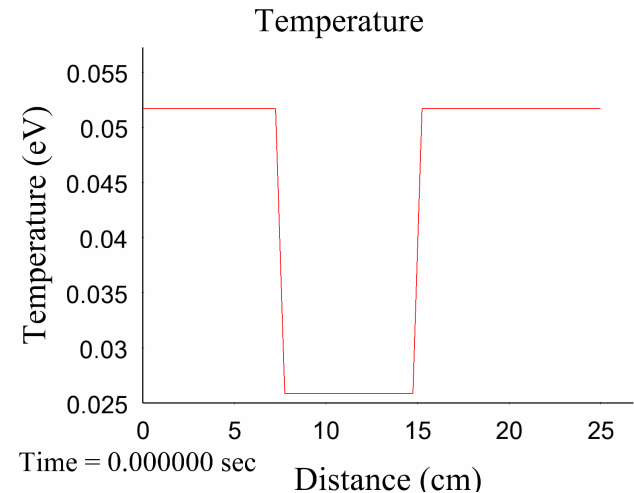
$$P = P(e, V, m_1, K, m_N, a_1, K, a_N), T_k = T_k(e, V, m_1, K, m_N, a_1, K, a_N)$$

- The pressure equation is in the form to take advantage of single material component EOS.
 - Most analytic equations of state in use for computational hydrodynamics are of the Grüneisen form:
e.g.
 - Perfect (ideal) gases
 - Mie-Grüneisen
 - JWL
- $$P - P_r(V) = \frac{G(V)}{V} (e - e_r(V))$$
- If all of the component equations of state are of the Grüneisen form, then the mixture pressure equation is linear.
 - Tabular equations of state can use a Newton method to compute the pressure
 - Numerical issues can occur due to poor interpolation
 - Bad sound speeds
 - Non-consistent thermodynamics (EOS not in free energy form)

- Simple translation of a hot slab of material
 - Perfect gases with $\gamma_1 = \gamma_2 = 1.4$
 - Specific heats differ by a factor of 2, $C_{V,1} = 4.141 \times 10^{10}$ ergs/gram/eV, $C_{V,2} = 8.282 \times 10^{10}$ ergs/gram/eV
 - Constant density, pressure, specific internal energy, and velocity

$$\begin{pmatrix} \rho \\ P \\ e \\ u \end{pmatrix} = \begin{cases} 1.17 \times 10^{-3} \text{ grams/cc} \\ 10^6 \text{ } \mu\text{bar} \\ 1.49 \times 10^9 \text{ ergs/gram} \\ 10^6 \text{ cm/second} \end{cases}, 0 \leq x \leq 25 \text{ cm}$$

$$T = \begin{cases} 5.17 \times 10^{-2} \text{ eV}, & 0 \leq x \leq 7.5, 15 \leq x \leq 25 \\ 2.59 \times 10^{-2} \text{ eV}, & 7.5 \leq x \leq 15 \end{cases}$$

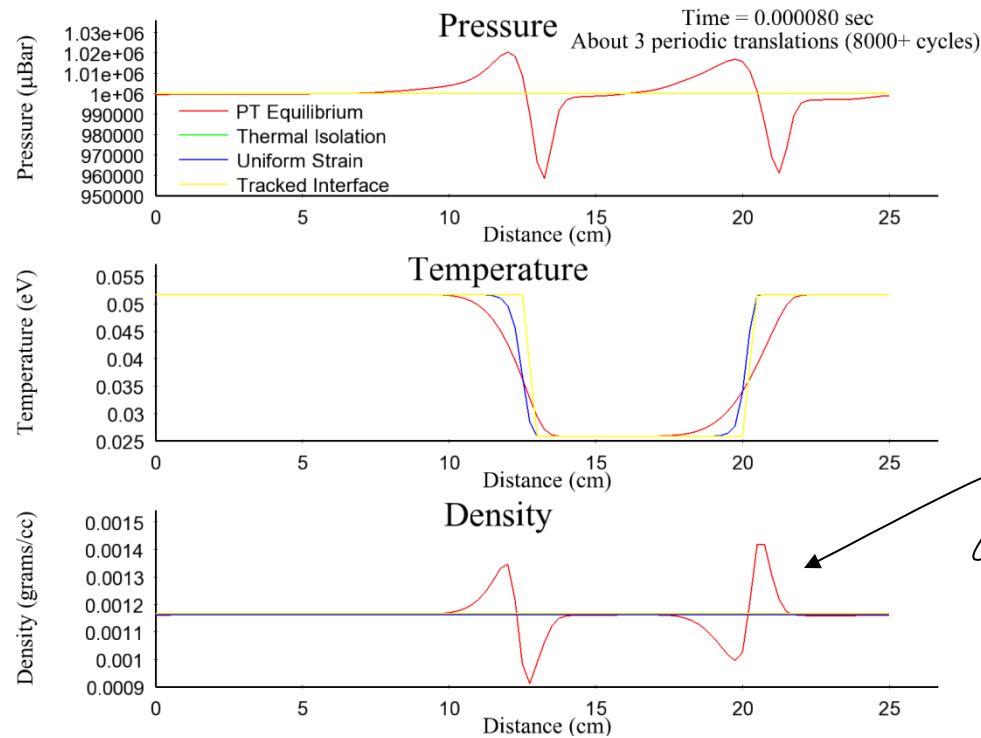


Test Problem: Hot Slab Translation



- Solution shows that P-T equilibrium has a significant effect on the flow state

≈ 8000 cycles



Transients created by the initial temperature discontinuity and then amplified by acoustic interactions.

Test Problem: Two Material Sod Problem



- Riemann problem with two material components
- Initial Conditions:

- Two material components, both perfect gases

- Component 1 initially in the interface $0 \leq x \leq 0.5$

$$\gamma_1 = 2.0, C_{V,1} = 10^{12} \text{ ergs/gram/eV}$$

- Component 2 initially in the interface $0.5 \leq x \leq 1$

$$\gamma_2 = 1.4, C_{V,2} = 10^{12} \text{ ergs/gram/eV}$$

- Isothermal initial conditions with a pressure/density jump across the interface

$$r(x,0) = \begin{cases} 10^{-3} \text{ grams/cc} & 0 \leq x \leq 0.5 \text{ cm} \\ 1.25 \times 10^{-4} \text{ grams/cc} & 0.5 \leq x \leq 1 \text{ cm} \end{cases}, P(x,0) = \begin{cases} 2.0 \times 10^6 \text{ mbar} & 0 \leq x \leq 0.5 \text{ cm} \\ 10^5 \text{ mbar} & 0.5 \leq x \leq 1 \text{ cm} \end{cases}$$

$$u(x,0) = 0 \quad 0 \leq x \leq 1 \text{ cm}$$

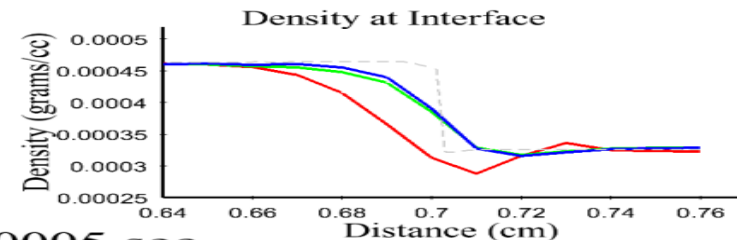
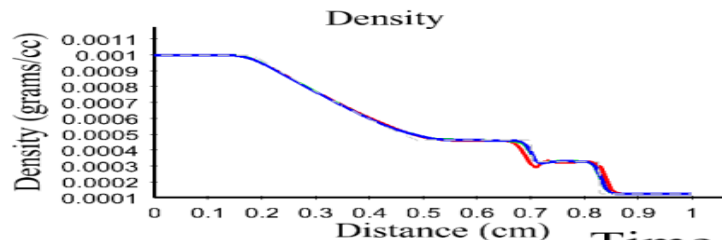
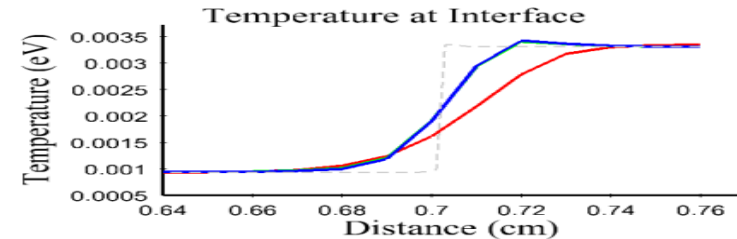
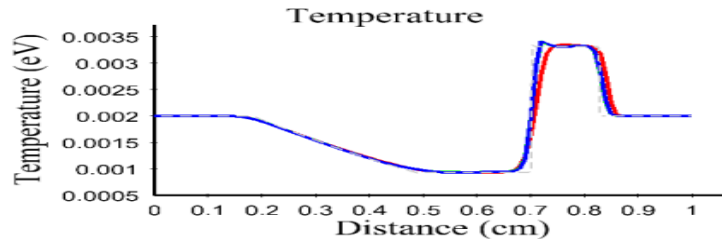
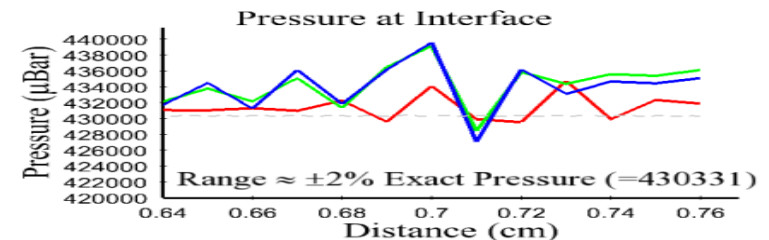
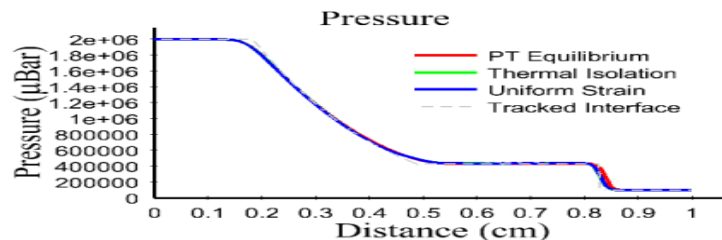
$$e(x,0) = 2.0 \times 10^9 \text{ ergs/gram} \quad 0 \leq x \leq 1 \text{ cm}, T(x,0) = 2.0 \times 10^{-3} \text{ eV} \quad 0 \leq x \leq 1 \text{ cm}$$

Test Problem: Two Material Sod Problem



- Main effect to temperature equilibrium is an increase in the width of the transition layer at the interface

11000 mesh zones



Time = 0.000005 sec

≈ 100 cycles

Test Problem: Strong Shock Refraction



- A Mach 15 shock accelerates the interface between two materials
- Initial Conditions:

- Spherical Symmetry

- Two material components, both perfect gases

- Component 1 initially in the interface $0 \leq x \leq 3$ cm

$$\gamma_1 = 1.1, C_{V,1} = 4 \times 10^{10} \text{ ergs/gram/eV}$$

- Component 2 initially in the interface $3 \leq x \leq 10$ cm

$$\gamma_2 = 2.0, C_{V,2} = 4 \times 10^6 \text{ ergs/gram/eV}$$

- Isothermal initial conditions with a density jump across the interface

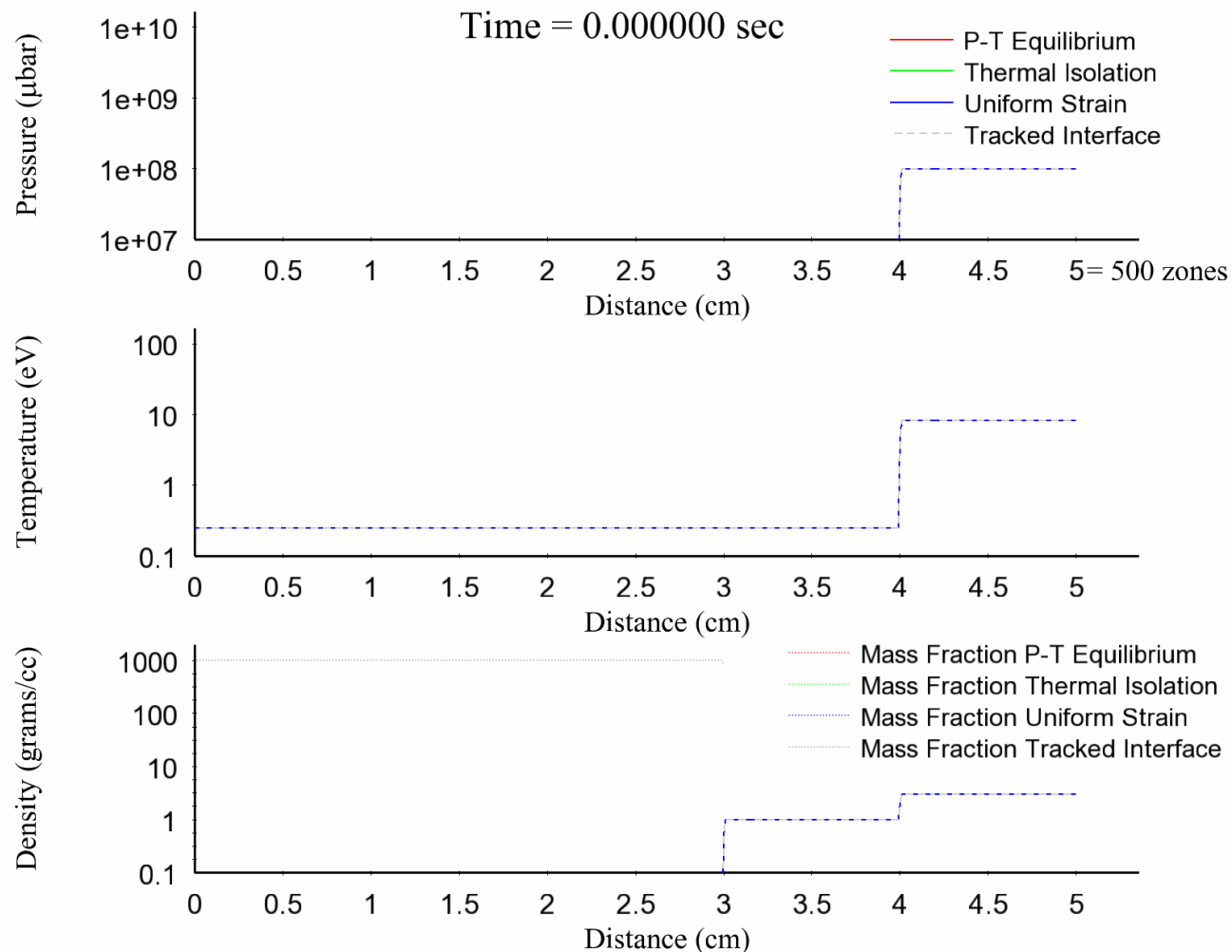
$$r(x,0) = \begin{cases} 10^{-3} \text{ grams/cc} & 0 \leq x \leq 3 \text{ cm} \\ 3 \text{ grams/cc} & 3 \leq x \leq 4 \text{ cm} \end{cases}, \quad e(x,0) = \begin{cases} 10^{10} \text{ ergs/gram} & 0 \leq x \leq 3 \text{ cm} \\ 10^6 \text{ ergs/gram} & 3 \leq x \leq 4 \text{ cm} \end{cases}$$

$$P(x,0) = 10^6 \text{ mbar} \mid 0 \leq x \leq 4 \text{ cm}$$

$$u(x,0) = 0 \mid 0 \leq x \leq 4 \text{ cm}, \quad T(x,0) = 0.25 \text{ eV} \mid 0 \leq x \leq 3 \text{ cm}$$

- A density of 3 grams/cc and a pressure of $10^8 \mu\text{bar}$ is initialized for the region $4 \leq x \leq 10$ cm, with zero initial velocity

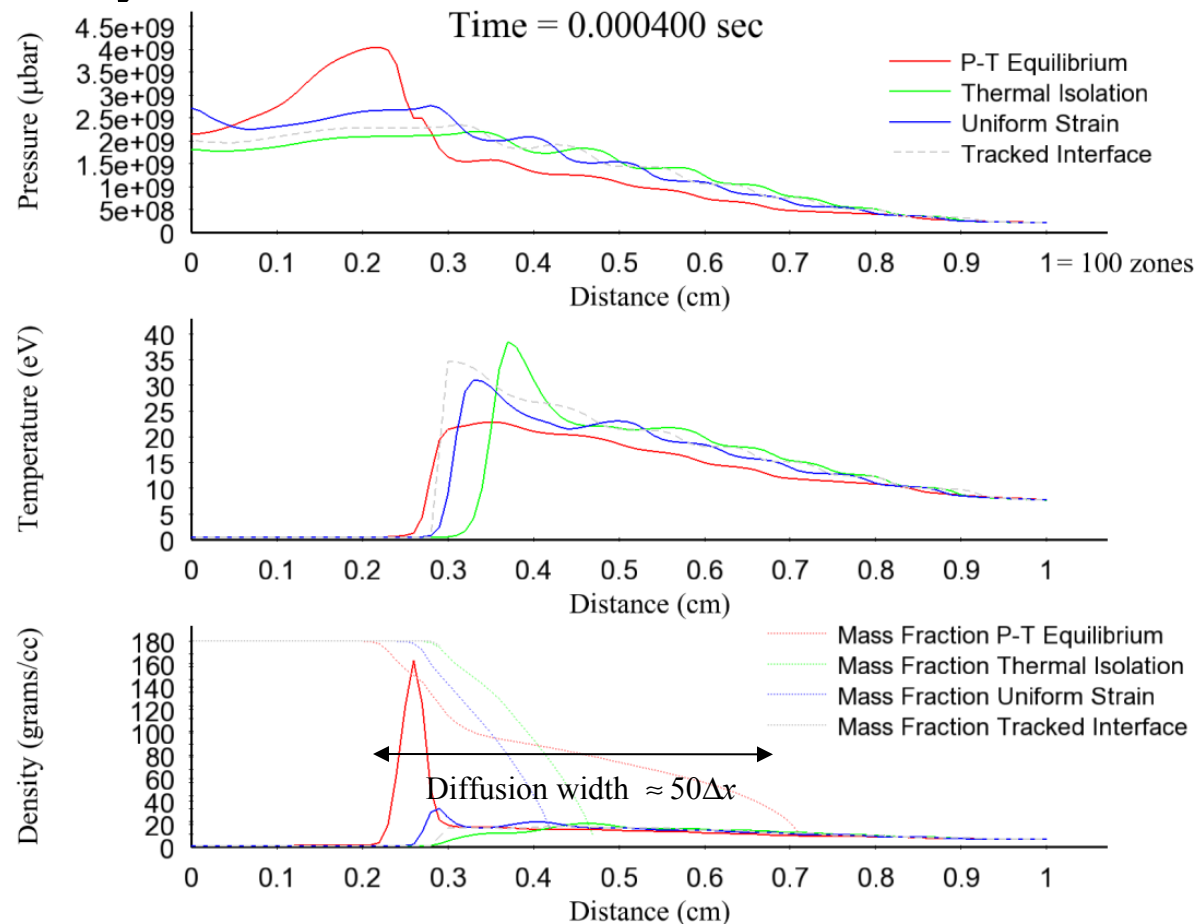
Test Problem: Strong Shock Refraction



Test Problem: Strong Shock Refraction



- P-T equilibrium has fast wave speed and much broader diffusion layer



- The thermal isolation and the uniform strain model are not in first principles conservation form
 - The “total” Hugoniot $e - e_0 = 0.5(P + P_0)(V_0 - V)$ is under-determined
 - Conservation of mass implies mass fractions are constant across shocks
 - For thermal isolation, a natural shock assumption is the separate Hugoniot solution:
 - Each component shocks to a common pressure using its separate Hugoniot equation
 - Solution to the mixture total specific internal energy, pressure, total specific volume Hugoniot
 - Ensures a C^2 combined rarefaction/Hugoniot wave curve
 - For uniform strain the natural assumption is that volume fractions are constant across shocks
 - Consistent with the advection assumption for volume fractions
 - Provides sufficient information to solve the “total” Hugoniot equation
 - Ensures a C^2 combined rarefaction/Hugoniot wave curve
- In both cases the effective shock Hugoniot is determined by the numerical viscosity of the finite difference scheme

- Ideally, for inviscid flows and immiscible flows FronTier style interface tracking is an ideal and nature approach
 - Not very easy to retrofit into existing codes
 - Framework in fact also supports miscible flows
 - Without tracking
 - With tracking – leaky interfaces
- Multi-Temperature flows can substantially reduce thermal and mixing layers
 - Issues with “poor” EOS’s (tabular)
- Multiple-pressure schemes are promising but introduce additional modeling concerns
 - E.g. velocity non-equilibrium
 - Relaxation equations are generally numerical.